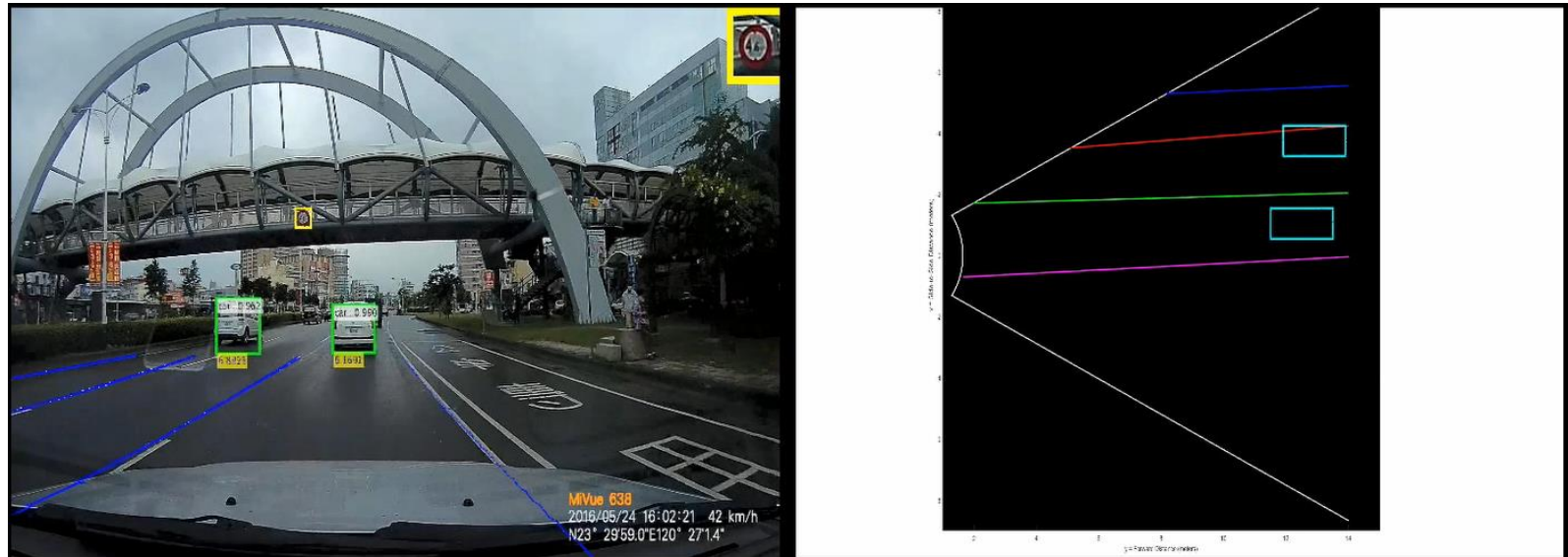


# Autonomous vehicle

## Scene understanding

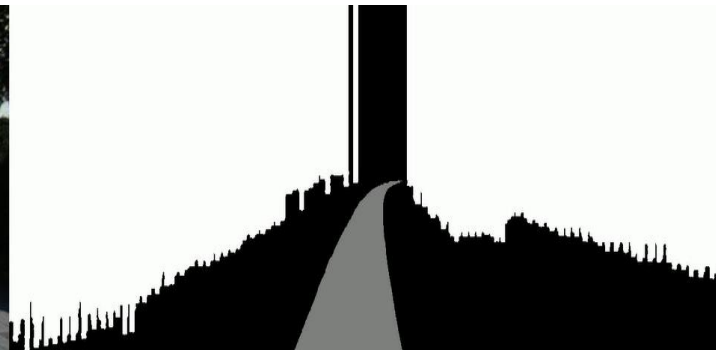
- Lane detection
- Traffic sign detection
- Vehicle detection and distance estimation
- Traffic scene semantic segmentation



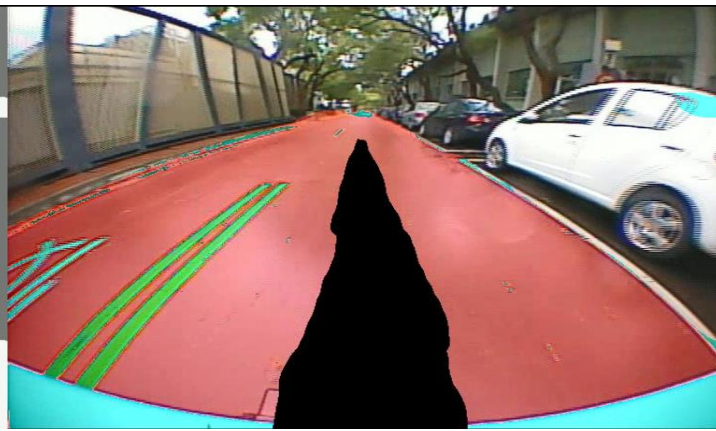
# Autonomous vehicle

## Path planning based on segmentation

- KITTI dataset
- Taiwan scene



Europe scene



Taiwan scene

# Scene understanding

- Lane and traffic sign detection
- Vehicle detection and distance estimation

# Scene understanding

- Traffic scene semantic segmentation

# Path planning on KITTI dataset

# Path planning on Taiwan scene

